



Attorney's Docket No. 010063-020

Patent

7-14-99

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re Patent Application of)
)
Genco GENOV, *et al.*) Group Art Unit: 2837
)
Continuing Prosecution Application of)
Application No.: 09/079,850)
) Examiner: Sircus, B.
)
Filed: May 15, 1998)
)
For: ROBOT HAVING MULTIPLE)
DEGREES OF FREEDOM)

PRELIMINARY AMENDMENT

Assistant Commissioner for Patents
Washington, D.C. 20231

Sir:

Prior to examination of the above-identified Continuing Prosecution Application,
please amend the above-identified application as follows:

In the Specification:

Page 17, line 22, delete "form" and insert --from--.

In the Claims:

Please add new Claims 51 - 58 as follows:

15.
--51. (New) A robotic arm structure providing θ motion and R motion,
comprising:
at least two links, each having a proximalmost end portion and a distalmost
end portion, with the θ motion being about a primary axis at the proximal end portion of a
proximalmost of the links and the R motion proceeding radially from the primary axis;

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